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2.5(RR) 2.5(R)(1arm&LHF) 1.5S No Arm 2.5S No Arm 3(RR) 3(R ...

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1 Arm J1:1 - A518 (W) T Arm J1:2 - A518 (E) - Straight

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0 5 10 15 20 25 30 35 40 1 2 4 MIPS Number Of Cores (Instruction Set Simulators) Avg. ISS MIPS Acc. System MIPS 3 VP Simulation Performance N Example: UC/MC VP Performance (MIPS)-Target SW: COREMARK/Linux-Test Single/dual/quad Core Systems-In-house Instruction Set Simulator (ISS)-OSCI/Accellera1SystemC KernelReduced Simulation 3th, 2024

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Simulated By MATLAB Software (Mittal And Nagrath, 2003). (a) (b) Fig. 2: Link Kinematic Of Right Arm In Position 1 (a) (b) Fig. 3: Link Kinematic Of Right Arm In Position 2 In Fig. 2a It Shows Exoskeleton Suit For Right Arm With Joint Angle $\theta z1$ And With Link Twist $\alpha z1$ In Fig. 2b. The Angle $\theta z0$ Is Attached With Human Body. 3th, 2024

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